# Low Power, Low Noise Ultrasound Receive Front-End Eight-Channels of LNA, VGA, AAF, CPS \& 12-Bit, 50MHz ADCs 

## Features

- 1.8V Analog/Digital supply
- 3.3V supply for CW Doppler output bias
- Fully differential inputs and outputs
- SPI programmable LNA gain $=14 \mathrm{~dB} / 18 \mathrm{~dB}$
- LNA input range 480 mV PP $/ 300 \mathrm{mV} \mathrm{V}_{\mathrm{PP}}$
- Dual mode active input impedance matching
- $1.1 \mathrm{nV} / \sqrt{\mathrm{Hz}}$ Input Voltage Noise at 5.0 MHz
- $1.0 \mathrm{pA} / \sqrt{\mathrm{Hz}}$ Input Current Noise at 5.0 MHz
- 0 to -47dB Linear-in-dB variable Gain of VCA
- 4 PGA Gain settings: 23.5, 29.0, 34.5 \& 40.0dB
- Third Order Anti-Aliasing Filter (AAF)
- Program/Auto-tracking AAF (6.6~15MHz)
- Integrated $8 \times 8$ Cross-Point Switch (CPS)
- SNR 66dB, SFDR 74dB for ADC
- Built-in reference voltage
- LVDS per ANSI-644
- Fast overload recovery time
- Low power $95 \mathrm{~mW} / \mathrm{ch}, 50 \mathrm{~mW} / \mathrm{ch}$ CW


## Applications

- Medical ultrasound imaging
- Portable ultrasound instrumentation
- Transducer signal processing


## General Description

The MD3872 is an eight-channel front-end receiver for medical ultrasound imaging. Its excellent low power dynamic performance is especially suitable for portable ultrasound applications.

The circuit of each channel is composed of a $14 \mathrm{~dB} / 18 \mathrm{~dB}$ low noise pre-amplifier (LNA), a voltage- controlled attenuator (VCA or TGC), a programmable gain amplifier (PGA), an anti-aliasing filter (AAF) and an analog-to-digital (ADC) converter. The gain and gain range of the VGA can be digitally configured separately. The gain of the PGA can be set to one of four discrete values: $23.5 \mathrm{~dB}, 29 \mathrm{~dB}, 34.5 \mathrm{~dB}$ or 40 dB . The VCA can be continuously varied by a control voltage from -47 dB to a maximum of 0 dB .

In CW mode, an integrated trans-conductance amplifier is driven by the LNA to generate differential output current. The resulting signal currents of each channel then connect to an $8 \times 8$ differential cross-point switch which can be programmed through the SPI.

The 12 -bit ADC is based on a pipeline structure to provide high static linearity. The data, clock, and frame alignment signal outputs are serial LVDS in binary format for each channel.

## Block Diagram



Ordering Information

| Part Number | Package Option | Packing |
| :--- | :--- | :--- |
| MD3872HF-G | 128-Lead TQFP (w/Heat Slug) | $90 /$ Tray |

-G indicates package is RoHS compliant ('Green’)

## Absolute Maximum Ratings

| Parameter | Value |
| :--- | ---: |
| $\mathrm{AV}_{\mathrm{DD}}$, Positive supply | -0.3 V to +2.0 V |
| $\mathrm{DV}_{\mathrm{DD}}$, Positive supply | -0.3 V to +2.0 V |
| $\mathrm{CWV}_{\mathrm{DD}}$, Positive supply | -0.3 V to +3.75 V |
| $\mathrm{~V}_{\mathbb{I}}$, Any input pin voltage range | -0.3 V to AV |
| Storage temperature | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Operating temperature | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied. Continuous operation of the device at the absolute rating level may affect device reliability. All voltages are referenced to device ground.

## Typical Thermal Resistance

| Package | $\boldsymbol{\theta}_{\text {ja }}$ |
| :--- | :--- |
| 128-Lead TQFP | $21^{\circ} \mathrm{C} / \mathrm{W}^{*}$ |

* 4"x3", 4-layer 1oz 16-via PCB



## Pin Configuration



128-Lead TQFP (top view)

## Package Marking



YY = Year Sealed $W W=$ Week Sealed
L = Lot Number C = Country of Origin
A = Assembler ID ____= "Green" Packaging
Package may or may not include the following marks: Si or \$iv
128-Lead TQFP

## Operating Supply Voltages

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=P V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| Sym | Parameter | Min | Typ | Max | Units | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{AV}_{\text {D }}$ | Analog circuit supply voltage | 1.71 | 1.8 | 1.89 | V | --- |
| DV ${ }_{\text {D }}$ | Digital circuit supply voltage | 1.71 | 1.8 | 1.89 | V | $\mathrm{f}_{\mathrm{s}}=40 \mathrm{MHz}$ |
|  |  | 1.80 | 1.90 | 1.98 |  | $\mathrm{f}_{\mathrm{s}}=50 \mathrm{MHz}$ |
| $C W V_{\text {DD }}$ | CW switch supply voltage | 3.14 | 3.3 | 3.47 | V | --- |
| $I_{\text {Avdo }}$ | AVDD per-chip | - | 360 | - | mA | --- |
|  | CWD mode | - | 190 | - |  |  |
| $\mathrm{I}_{\text {DVDD }}$ | DVDD supply current | - | 70 | 100 | mA | $\mathrm{f}_{\mathrm{s}}=40 \mathrm{MHz}$ |
|  |  | - | 94 | 140 |  | $\mathrm{f}_{\mathrm{s}}=50 \mathrm{MHz}$ |
| $\mathrm{I}_{\text {CVDD }}$ | CVDD supply current | - | 0.80 | 1.0 | mA | 8-channel total |
| Power | Per-channel at 40MSPS | - | 95 | - | mW | --- |
|  | Per-channel at CW mode | - | 50 | - |  |  |
|  | Power-down | - | - | 1.0 |  | 8-channel total |
|  | Standby | - | 100 | - |  |  |

Low Noise Preamplifier
(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, G_{L N A}=18 \mathrm{~dB}, T_{A}=25^{\circ} \mathrm{C}$ )

| Sym | Parameter | Min | Typ | Max | Units | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{G}_{\text {LNA }}$ | Pre-amplifier gain | - | 14/18 | - | dB | Selectable |
| $\mathrm{R}_{\text {IN }}$ | Input resistance | - | 15 | - | k $\Omega$ | Without active termination |
| $\mathrm{C}_{\text {IN }}$ | Input capacitance | - | 10 | - | pF | Without active termination |
| $\mathrm{I}_{\text {BIAS }}$ | Input bias current | - | 1.0 | - | nA | From ESD leakage |
| $\mathrm{V}_{\text {IN }}$ | Input voltage range | - | $\pm 240$ | - | mV | $\mathrm{GAIN}_{\text {LNA }}=1$ |
|  |  | - | $\pm 150$ | - |  | $\mathrm{GAIN}_{\text {LNA }}=0$ |
| $\begin{aligned} & \mathrm{V}_{\text {LNA }} \\ & \text { NOISE } \end{aligned}$ | Input voltage noise, 5MHz | - | 1.3 | - | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ | LNA Gain of 14dB |
|  |  | - | 1.1 | - |  | LNA Gain of 18dB |
| $\mathrm{I}_{\text {IN-NOISE }}$ | Input current noise | - | 1.05 | - | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ | Without active termination |
| NF | Noise figure | - | 4.4 | - | dB | $\mathrm{f}=5.0 \mathrm{MHz},$ <br> without active termination |
|  |  | - | 6.0 | - |  | $\begin{aligned} & R_{S}=R_{I N}=50 \Omega, \\ & f=5.0 \mathrm{MHz} \text { with active termination } \end{aligned}$ |
| BW | LNA -3dB bandwidth | - | 65 | - | MHz | Small signal bandwidth |

## Overall Channel Characteristics

((Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| Gain | Whole channel gain | - | 58 | - | dB | Without active termination, max. gain |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CH-NoISE }}$ | Input voltage noise, 5.0 MHz | - | 2.0/1.5 | - | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ | LNA gain of 14 or 18 dB |
| SFDR | Spurious-free dynamic range, $-1 \mathrm{dBFS}, 5 \mathrm{MHz}$ | - | 63.2 | - | dBc | 40Msps |
|  |  | - | 62.1 | - |  | 50Msps |
| SNRFS | Signal to noise ratio at full scale, -1dBFS, 5 MHz | - | 56.3 | - | dBc | 40Msps |
|  |  | - | 56.2 | - |  | 50Msps |
| HD2 | Second harmonic distortion, $-1 \mathrm{dBFS}, 5 \mathrm{MHz}, 40 \mathrm{~dB}$ gain | - | -72 | - | dBc | 40Msps |
|  |  | - | -68 | - |  | 50Msps |
| HD3 | Third harmonic distortion, $-1 \mathrm{dBFS}, 5 \mathrm{MHz}, 40 \mathrm{~dB}$ gain | - | -63 | - | dBc | 40Msps |
|  |  | - | -62 | - |  | 50Msps |
| IMD | IMD, two-tone | - | -63 | - | dBc | $\begin{aligned} & \mathrm{f} 1=5.0 \mathrm{MHz}, \mathrm{f} 2=6.0 \mathrm{MHz}, \\ & \text { at }-7.0 \mathrm{dBFS}, 40 \mathrm{~dB} \text { gain } \end{aligned}$ |
| CSTK | Crosstalk | - | -70 | - | dB | $1.0 \mathrm{MHz}, 1 \mathrm{~V}_{\mathrm{PP}}$ at adjacent channel |
| $\Delta \mathrm{t}_{\mathrm{gd}}$ | Group delay variation | - | $\pm 2.0$ | - | ns | 2.0 to 10 MHz , max gain range |
| $\mathrm{t}_{\text {OLR }}$ | Overload recovery time | - | 5.0 | - | ns | 8 dB gain, $\mathrm{V}_{\text {IN }} 10 \mathrm{MHz} 10 \mathrm{mV} \mathrm{V}_{\mathrm{PP}}$ to $0.5 \mathrm{~V}_{\text {PP }}$ step |
| $\mathrm{f}_{\text {CHP }}$ | High-pass cutoff frequency | - | 50 | - | kHz | --- |

Gain Control and Accuracy
(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| Sym | Parameter | Min | Typ | Max | Units | Conditions |
| :---: | :--- | :---: | :---: | :---: | :---: | :--- |
| $\mathrm{V}_{\text {TGC }}$ | Gain control voltage | 0 | - | 1.8 | V | Linear in dB, see Gain scaling diagram |
| $\mathrm{V}_{\text {GSC }}$ | Gain slope voltage | 1.44 | - | 1.8 | V | $\sim 62 \mathrm{~dB} / \mathrm{V}$ at 1.44 V and $47.5 \mathrm{~dB} / \mathrm{V}$ at 1.8 V |
| $\mathrm{G}_{\text {RANGE }}$ | Gain range | - | 46.5 | - | dB | $\mathrm{GSC}=0$ to +1.8 V |
| $\mathrm{G}_{\text {SLP }}$ | Gain slope | - | 47.5 | - | $\mathrm{dB} / \mathrm{V}$ | $\mathrm{GSC}=+1.8 \mathrm{~V}$ |
| $\mathrm{G}_{\text {MAT }}$ | Ch. to ch. Gain matching | - | $\pm 1.5$ | - | dB | $0.4<\mathrm{V}_{\text {TGC }}<1.2 \mathrm{~V}$ |
| $\mathrm{E}_{\text {GAIN }}$ | Gain error | -1.6 | $\pm 0.5$ | +1.6 | dB |  |
| $\mathrm{~V}_{\text {OS }}$ | Output offset voltage | - | 15 | - | LSB | $\mathrm{EXT}=$ Lo (internal reference) |
| $\mathrm{R}_{\text {GSC }}$ | Input resistance of GSC | - | 90 | - | $\mathrm{k} \Omega$ | $\mathrm{VTGC}=0 \mathrm{~V}$ |
| $\mathrm{I}_{\text {TGC }}$ | Input current of TGC | -2.0 | - | +2.0 | hA | For the control range of 0 V to 1.8 V |
| $\mathrm{td}_{\text {TGC }}$ | Response time | - | 500 | - | ns | 0 to $90 \%$ full Gain change |

## Logic Inputs Characteristics

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| $\mathrm{V}_{\mathrm{IH}}$ | High-level input voltage | $0.8 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V | -- |
| :---: | :--- | :---: | :---: | :---: | :---: | :--- |
| $\mathrm{V}_{\mathrm{IL}}$ | Low-level input voltage | - | - | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | V | --- |
| $\mathrm{I}_{\mathrm{HH}}$ | High-level input current | - | 1.0 | - | $\mu \mathrm{A}$ | --- |
| $\mathrm{I}_{\mathrm{IL}}$ | Low-level input current | - | 1.0 | - | $\mu \mathrm{A}$ | --- |
| $\mathrm{V}_{\mathrm{OH}}$ | High-level output voltage <br> $\left(\mathrm{I}_{\mathrm{OH}}=0.5 \mathrm{~mA}\right)$ | - | 1.79 | - | V | --- |
| $\mathrm{V}_{\mathrm{OL}}$ | Low-level output voltage <br> $\left(\mathrm{I}_{\mathrm{OL}}=0.5 \mathrm{~mA}\right)$ | - | 0.05 | - | V | --- |
| $\mathrm{C}_{\mathrm{IN}}$ | Input capacitance | - | 2.0 | - | pF | --- |

## LVDS DC and Timing Characteristics

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| $V_{\text {D }}$ | Differential output voltage | 250 | - | 450 | mV | --- |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {ocom }}$ | Output common-mode voltage | 1.13 | - | 1.37 | V | --- |
| $\mathrm{R}_{\text {TERM }}$ | LVDS termination resistor | - | 100 | - | $\Omega$ | --- |
| $\mathrm{t}_{\mathrm{R}}$ | Rise time (20\% to $80 \%$ ) | - | 800 | - | ps | --- |
| $\mathrm{t}_{\mathrm{F}}$ | Fall time (80\% to 20 \%) | - | 800 | - | ps | --- |
| $\mathrm{t}_{\text {DCLKWH }}$ | DCLK output width high | - | 4.1 | - | ns | $\mathrm{F}_{\mathrm{s}}=40 \mathrm{Msps}$ |
| $\mathrm{t}_{\text {DCLKWL }}$ | DCLK output width low | - | 4.1 | - |  |  |
| $\mathrm{t}_{\mathrm{D2D}}$ | Data valid to DCLK rise/fall | - | $\mathrm{t}_{s} / 24$ | - |  |  |
| $\mathrm{t}_{\text {F2D }}$ | FCLK rise to DCLK rise | - | $\mathrm{t}_{s} / 24$ | - |  |  |
| $\mathrm{t}_{\text {c2F }}$ | CLK rise to FCLK rise | - | $\mathrm{t}_{\mathrm{s}} / 2+\mathrm{t}_{\text {PRP }}$ | - |  |  |

## Internal and External Reference Characteristics

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| Sym | Parameter | Min | Typ | Max | Unit | Conditions |
| :---: | :--- | :---: | :---: | :---: | :---: | :--- |
| $\mathrm{V}_{\text {REF+ }}$ | ADC reference top voltage | - | 1.4 | - | V | ADC reference voltages, decou- |
| $\mathrm{V}_{\text {REF- }}$ | ADC reference bottom voltage | - | 0.4 | - | V | pling capacitors required |

## CW Doppler Mode Characteristics

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| $\mathrm{g}_{\mathrm{m}}$ | Transconductance | - | $9.5 / 15.2$ | - | $\mathrm{mA} / \mathrm{V}$ | LNA Gain $=14 / 18 \mathrm{~dB}$ |
| :---: | :--- | :---: | :---: | :---: | :---: | :--- |
| $\mathrm{~V}_{\text {COMM }}$ | Common-mode voltage | 1.5 | - | 3.6 | V | CW Doppler output pins |
| $\mathrm{V}_{\text {CW-NOISE }}$ | Input-referred noise voltage | - | $1.75 / 1.45$ | - | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ | LNA Gain 14/18dB, $\mathrm{R}_{\mathrm{S}}=0, \mathrm{R}_{\mathrm{FB}}=\infty$ |
| $\mathrm{I}_{\text {OUT-BIAS }}$ | Output DC bias | - | 2.8 | - | mA | Per channel |
| $\mathrm{I}_{\text {OUT-SWING }}$ | Maximum output swing | - | $\pm 2.3$ | - | $\mathrm{mA}_{\text {P-P }}$ | --- |

## Switching AC Characteristics

(Over operating conditions unless otherwise specified, $A V_{D D}=D V_{D D}=1.8 \mathrm{~V}, C W V_{D D}=+3.3 \mathrm{~V}, R_{S E L}=H i, R_{S}=50 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )

| $\mathrm{F}_{\mathrm{s}}$ | ADC conversion rate | 20 | - | 50 | MSPS | --- |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {s }}$ | Clock period | 20 | - | 50 | ns | --- |
| $\mathrm{t}_{\text {CLKWH }}$ | Clock pulse-width high | - | 12.5 | - | ns | --- |
| $\mathrm{t}_{\text {cLKWL }}$ | Clock pulse-width low | - | 12.5 | - | ns | --- |
| $\mathrm{t}_{\text {PRP }}$ | ADC clock propagation delay | - | 2.6 | - | ns | --- |
| $\mathrm{PL}_{\text {d }}$ | Pipeline latency delay | - | 5.5 | - | cycle | --- |
| $\mathrm{t}_{\text {SBY_DWN }}$ | Time to standby | - | 1.0 | - | $\mu \mathrm{s}$ | --- |
| $\mathrm{t}_{\text {sBr_wup }}$ | Time to wakeup | - | 10 | - | $\mu \mathrm{s}$ | --- |
| $\mathrm{t}_{\text {PD_ }}$ Ww | Time to power down | - | 1.0 | - | $\mu \mathrm{s}$ | --- |
| $\mathrm{t}_{\text {PD_UP }}$ | Time to power up | - | 10 | - | ms | --- |
| $\mathrm{t}_{1}$ | SDI valid to SCK setup time | 0 | 2.0 | - | ns | See serial interface timing diagram |
| $\mathrm{t}_{2}$ | SDI valid to SCK hold time | 4.0 | - | - |  |  |
| $\mathrm{t}_{3}$ | SCK high time | 9.0 | 10 | - |  |  |
| $\mathrm{t}_{4}$ | SCK low time | 9.0 | 10 | - |  |  |
| $\mathrm{t}_{5}$ | CSB pulse width | 9.0 | 10 | - |  |  |
| $\mathrm{t}_{6}$ | SCK high to CSB low | - | 4.5 | - |  |  |
| $\mathrm{f}_{\text {sck }}$ | Serial clock max frequency | 50 | - | - | MHz | --- |

12-Bit ADC Digital Output Coding Table

| Level | ADC Input Voltage | Binary Digital Output | Notes |
| :---: | :---: | :---: | :--- |
| 4094 | $\mathrm{~V}_{\mathbb{I N}}>+0.999756 \mathrm{~V}$ | 111111111110 | --- |
| $\ldots$ | $\ldots$ | $\ldots$ | --- |
| 2048 | $+0.000244 \mathrm{~V}<\mathrm{V}_{\mathbb{I N}}<+0.000732 \mathrm{~V}$ | 100000000000 | --- |
| 2047 | $-0.000244 \mathrm{~V}<\mathrm{V}_{\mathbb{I N}}<+0.000244 \mathrm{~V}$ | 011111111111 | --- |
| $\ldots$ | $\ldots$ | $\ldots$ | --- |
| 0 | $\mathrm{~V}_{\mathbb{I N}}<-0.999756 \mathrm{~V}$ | 000000000000 | --- |

## SPI Registers Address and Data Table

| MSB (shift in first) |  | SPI Register Data Word |  |  |  |  |  |  |  |  | LSB |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADDR[3:0] Hex | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| 0 | - | STEP[2:0](Alignment Step Size) |  |  | OUTDLY[5:0] <br> (All channel OUTLVDS alignment delay setting) |  |  |  |  |  | ATP[1:0] |  |
| 1 | TPD1[11:0] (LVDS Testing Pattern \#1) |  |  |  |  |  |  |  |  |  |  |  |
| 2 | CW1[5:0] (Channel 1 CW mode control) |  |  |  |  |  | CW2[5:0] (Channel 2 CW mode control) |  |  |  |  |  |
| 3 | CW3[5:0] (Channel 3 CW mode control) |  |  |  |  |  | CW4[5:0] (Channel 4 CW mode control) |  |  |  |  |  |
| 4 | CW5[5:0] (Channel 5 CW mode control) |  |  |  |  |  | CW6[5:0] (Channel 6 CW mode control) |  |  |  |  |  |
| 5 | CW7[5:0] (Channel 7 CW mode control) |  |  |  |  |  | CW8[5:0] (Channel 8 CW mode control) |  |  |  |  |  |
| 6 | - | - | - | $\frac{\mathrm{CW} /}{\mathrm{TGC}}$ | CHOFF[7:0] (TGC Per Channel Power Off, 0=ON 1=OFF) |  |  |  |  |  |  |  |
| 7 | - | - | AAF[1:0] |  | - | PDC | FLEX | - | SWLNA | GAIN LNA | PG[1:0] |  |
| 8 | - | - | CTL | PR[5:2] |  |  |  | - | AAF[5:2] |  |  |  |
| 9 | - | - | - | - | ADCPD[7:0] (ADC Per Channel Power Down, $0=$ ON $1=\mathrm{OFF}$ ) |  |  |  |  |  |  |  |
| A | - | - | - | - | Reserved Default all 0 |  |  |  |  |  |  |  |
| B | SWING[2:0] |  |  | - | Reserved Default all 0 |  |  |  |  |  |  |  |
| C | TPDC[11:0] (LVDS Testing Pattern \#C) |  |  |  |  |  |  |  |  |  |  |  |
| D | FDDLY[5:0] (FCLK and DCLK alignment delay setting) |  |  |  |  |  | - | - | - | - | - | - |
| E | Reserved Default all 0 |  |  |  |  |  |  |  |  |  |  |  |
| F | ADDR[3:0] to READ Back |  |  |  | - | - | - | - | - | - | - | - |

## Note:

A bit marked as "-" means do-not-care whether it is set to " 1 " or " 0 ".

## TGC and GSC Voltage for Gain Scaling LNA Feedback Configurations




ADDR=0 D[10:8]
STEP[2:0] LVDS Delay Step Size Control Table

| STEP[2:0] | Delay Time Step Size |  |
| :---: | :---: | :---: |
| 000 | $100 \%$ (Default value) | 120ps |
| 001 | $133 \%$ | 160 ps |
| 010 | $200 \%$ | 240 ps |
| 011 | $400 \%$ | 480 ps |
| 100 | $50 \%(\mathrm{~min})$ | 60 ps |
| 101 | $57 \%$ | 69 ps |
| 110 | $67 \%$ | 80 ps |
| 111 | $80 \%$ | $96 p s$ |

Note:

1. LDVS delay time step size control. Each bit will change the delay step size by 120 ps. Setting a different value than 00 will change the DLOUT[5:0] and FDDLY[5:0] delay-time's step-size.
2. If $f_{s}=50 \mathrm{MHz}$ it is suggested that you use the minimum $\operatorname{STEP[2:0]}=100$.

ADDR=0 D[7:2]
OUTDLY[5:0] LVDS ADC Data Output Delay Adjustment Table

| OUTDLY[5:0] | Typical Rise Time Delay (ps) | Typical Fall Time Delay (ps) |
| :---: | :---: | :---: |
| 000000 | 655 | 685 |
| 000001 | 766 | 805 |
| $\ldots \ldots$ | DELAY $=139.4 \times$ FDDLY +655 | DELAY $=148.5 \times$ FDDLY +699 |
| 111110 | 9241 | 9824 |
| 111111 | 9340 | 9951 |

## Note:

OUTDLY[5:0] and ADDR = D, FDDLY[5:0] are for LVDS data OUT8-1, DCLK and FCLK alignment delay time setting.
ADDR=0 D[1:0]
ATP[1:0] LVDS Alignment Test Pattern Control Table

| D1 | D0 | LVDS Output Description |
| :---: | :---: | :--- |
| 0 | 0 | Latest ADC Results. |
| 0 | 1 | TPDC[11:0] data written in ADDR[C], the LVDS testing data \#C. |
| 1 | 0 | Fixed predefined test pattern: "1000 0000 0000" |
| 1 | 1 | TPD1[11:0] data written in ADDR[1], the LVDS testing data \#1. |

ADDR=2,3,4 or 5 D[5:0] or D[11:6]
CWn Cross-Point Switch Control Table ( $\mathrm{n}=1$ to 8 for Ch1 to Ch8)

| C5 | C4 | C3 | C2 | C1 | C0 | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| 0 | X | X | X | X | X | CW channel Power Down |
| 1 | 0 | X | 0 | 0 | 0 | Differential mode CW1+, CW1- |
| 1 | 0 | X | 0 | 0 | 1 | Differential mode CW2+, CW2- |
| 1 | 0 | X | 0 | 1 | 0 | Differential mode CW3+, CW3- |
| 1 | 0 | X | 0 | 1 | 1 | Differential mode CW4+, CW4- |
| 1 | 0 | X | 1 | 0 | 0 | Differential mode CW5+, CW5- |
| 1 | 0 | X | 1 | 0 | 1 | Differential mode CW6+, CW6- |
| 1 | 0 | X | 1 | 1 | 0 | Differential mode CW7+, CW7- |
| 1 | 0 | X | 1 | 1 | 1 | Differential mode CW8+, CW8- |
| 1 | 1 | 0 | 0 | 0 | 0 | Single-ended mode CW1+ |
| 1 | 1 | 0 | 0 | 0 | 1 | Single-ended mode CW2+ |
| 1 | 1 | 0 | 0 | 1 | 0 | Single-ended mode CW3+ |
| 1 | 1 | 0 | 0 | 1 | 1 | Single-ended mode CW4+ |
| 1 | 1 | 0 | 1 | 0 | 0 | Single-ended mode CW5+ |
| 1 | 1 | 0 | 1 | 0 | 1 | Single-ended mode CW6+ |
| 1 | 1 | 0 | 1 | 1 | 0 | Single-ended mode CW7+ |
| 1 | 1 | 0 | 1 | 1 | 1 | Single-ended mode CW8+ |
| 1 | 1 | 1 | 0 | 0 | 0 | Single-ended mode CW1- |
| 1 | 1 | 1 | 0 | 0 | 1 | Single-ended mode CW2-- |
| 1 | 1 | 1 | 0 | 1 | 0 | Single-ended mode CW3- |
| 1 | 1 | 1 | 0 | 1 | 1 | Single-ended mode CW4- |
| 1 | 1 | 1 | 1 | 0 | 0 | Single-ended mode CW5- |
| 1 | 1 | 1 | 1 | 0 | 1 | Single-ended mode CW6- |
| 1 | 1 | 1 | 1 | 1 | 0 | Single-ended mode CW7- |
| 1 | 1 | 1 | 1 | 1 | 1 | Single-ended mode CW8- |

ADDR=6 D[8]

## CW/TGC TGC or CW Mode Control

| 0 | TGC mode. $\mathrm{CH}[8: 1]=1$ for TGC (LNA+VGA+AAF) channel 1-8 power down individually. |
| :---: | :--- |
| 1 | CW mode. MSB (C5) of CWn[5:0] per channel control power down channel individually. |

## Note:

See CWn Cross-Point Switch Control Table

ADDR=6 D[7:0]
CHOFF[7:0] TGC (LNA+VGA+AAF) Channel Power Control Table

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TGC Ch8 | TGC Ch7 | TGC Ch6 | TGC Ch5 | TGC Ch4 | TGC Ch3 | TGC Ch2 | TGC Ch1 |

## Note:

$0=$ ON, 1 = OFF (power down)

ADDR=7 D[9:8]
AAF[1:0] Cutoff Frequency and Control Table

| AAF[1:0] | 3rd Order Anti-Aliasing Filter Corner Freq fAAF |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Typ | Max | Units | Note |
| 00 | 6.6 | FS/3 | 15 | MHz | $100 \%$ as default |
| 01 | 115 |  |  |  | $\%$ |
| 10 | Set by AAF[5:2] | MHz of default |  |  |  |
| 11 | 85 | $\%$ | $\%$ of default |  |  |

## ADDR=7 D[6]

PDC Enable External Biasing

| 0 | Disable external Biasing for VGA |
| :--- | :--- |
| 1 | Enable external Biasing for VGA |

## ADDR=7 D[5]

## FLEX AAF Tracking Auto-Tuning Control

| 0 | FLEX $=0$ disable continuous auto-tuning for AAF tracking the input clock. |
| :--- | :--- |
| 1 | FLEX=1 enable continuous auto-tuning for AAF tracking the input clock, |

## Note:

FLEX must be set to " 1 " first then to "0" to turn off the AFF auto-tracking after the chip power on, although the poweron default is $F L E X=0$.

ADDR=7 D[3]
SWLNA LNA Gain Switches Control

| 0 | SW1~8 Off, disconnecting $R_{\mathrm{t} 2}$ to PA- terminal. |
| :--- | :--- |
| 1 | SWLNA=1 On, connecting $\mathrm{R}_{\mathrm{f} 2}$ to PA- terminal. |

ADDR=7 D[2]
GAINLNA LNA Gain Control

| 0 | LNA gain set to 18 dB |
| :--- | :--- |
| 1 | LNA gain set to 14 dB |

ADDR=7 D[1:0]
PG[1:0] Gain Setting

| 00 | Select 23.5dB Gain Setting |
| :--- | :--- |
| 01 | Select 29.0dB Gain Setting |
| 10 | Select 34.5dB Gain Setting |
| 11 | Select 40.0dB Gain Setting |

ADDR=8 D[9]
CTL AAF Frequency Programming Enable

| 0 | AAF use AAF[5:2] tracking the sampling frequency. |
| :--- | :--- |
| 1 | AAF use PR[5:2] programmed frequency. |

## Note:

See AAF and PR tables

ADDR=8 D[8:5]
PR[5:2] Cutoff Frequency Direct Control Table (CTL = 1)

| PR[5:2] | Reference -3dB Cut-off Frequency (MHz) |  |
| :---: | :---: | :---: |
| 0000 | 15.8 |  |
| 0001 | 14.3 |  |
| 0010 | 12.9 |  |
| 0011 | 11.8 | Nate built-in AAF frequency |
| 0100 | 10.8 |  |
| 0101 | 9.9 |  |
| 0110 | 9.2 |  |
| 0111 | 8.6 |  |
| 1000 | 8.0 |  |
| 1001 | 7.6 |  |
| 1010 | 7.1 |  |
| 1011 | 6.8 |  |
| 1100 | 6.4 |  |
| 1101 | 6.0 |  |
| 1110 | 5.8 |  |
| 1111 | 5.6 |  |

ADDR=8 D[3:0]

## AAF[5:2] Cutoff Frequency Control Table (AAF[1:0]=10)

| SPI Control Register Data Bits |  |  |  |  |  |  |  |  | Typical -3dB Cut-off Frequency (MHz) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AAF5 | AAF4 | AAF3 | AAF2 | $F_{S}=50 \mathrm{MHz}$ | $F_{S}=40 \mathrm{MHz}$ | $F_{S}=30 \mathrm{MHz}$ | $F_{S}=20 \mathrm{MHz}$ |  |  |  |  |  |
| 1 | 1 | 1 | 1 | 15.6 | 12.5 | 9.5 | 6.1 |  |  |  |  |  |
| 1 | 1 | 1 | 0 | 13.4 | 10.7 | 8.7 | 5.9 |  |  |  |  |  |
| 1 | 1 | 0 | 1 | 12.8 | 10.2 | 8.1 | 5.8 |  |  |  |  |  |
| 1 | 1 | 0 | 0 | 11.9 | 9.5 | 7.6 | 5.8 |  |  |  |  |  |
| 1 | 0 | 1 | 1 | 10.9 | 8.7 | 7.0 | 5.8 |  |  |  |  |  |
| 1 | 0 | 1 | 0 | 10.0 | 8.1 | 6.7 | 5.8 |  |  |  |  |  |
| 1 | 0 | 0 | 1 | 9.5 | 7.6 | 6.2 | 5.8 |  |  |  |  |  |
| 1 | 0 | 0 | 0 | 8.8 | 7.0 | 6.0 | 5.8 |  |  |  |  |  |

ADDR=9 D[7:0]
ADCPD[7:0] ADC Channel Power down Control Table

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADC Ch8 | ADC Ch7 | ADC Ch6 | ADC Ch5 | ADC Ch4 | ADC Ch3 | ADC Ch2 | ADC Ch1 |

## Note:

$0=$ ON, 1 = OFF (power down)

SWING[2:0] LVDS Output Swing Control Table

| SWING[2:0] | LVDS Output Swing Amplitude (mV) |
| :---: | :---: |
| 000 | 350 (Default value) |
| 001 | 263 |
| 010 | 175 |
| 011 | 88 |
| 100 | 700 |
| 101 | 613 |
| 110 | 525 |
| 111 | 438 |

ADDR=D D[11:6]
FDDLY[5:0] LVDS FCLK \& DCLK Delay Adjustment Table

| FDDLY[5:0] | Typical Rise Time Delay (ps) | Typical Fall Time Delay (ps) |
| :---: | :---: | :---: |
| 000000 | 655 | 685 |
| 000001 | 766 | 805 |
| $\ldots \ldots$ | DELAY $=139.4 \times$ FDDLY +655 | DELAY $=148.5 \times$ FDDLY +699 |
| 111110 | 9241 | 9824 |
| 111111 | 9340 | 9951 |

## Note:

OUTDLY[5:0] and ADDR=D, FDDLY[5:0] are for LVDS data OUT8-1, DCLK and FCLK alignment delay time setting.

ADDR=F D[11:8]

## ADDR[3:0] Register Contain Read Back Address

| 0000 | Read Back Register ADDR $=0 \times 0$ |
| :---: | :--- |
| 0001 | Read Back Register ADDR $=0 \times 1$ |
| $\ldots$ | $\ldots$ |
| 1110 | Read Back Register ADDR $=0 x E$ |

## SPI Timing Diagram



## SPI Data Diagram



## LVDS Timing Diagram



## General Description

The MD3872 has eight identical front-end receiver channels designed for medical ultrasound imaging. Each channel consists of a low noise preamplifier (LNA), a variable gain amplifier (VGA), an anti-aliasing filter (AAF), and a 12-bit analog-to-digital converter (ADC). The VGA consists of two parts, a voltage controlled attenuator (VCA), and a programmable gain amplifier (PGA). The gain and gain range of the VGA can be digitally configured separately. The gain of the LNA is selectable. The differential outputs of each LNA can also be used to provide amplified RF signals for the CW Doppler beamforming processing. The voltage-controlled-gain TGC attenuator can be continuously varied by a control voltage at the TGC pin from -47 dB to a maximum of 0 dB . The gain of the TGC curve is linear-in-dB, and the slope of the curve can be adjusted by the input voltage of GSC pin for all the eight channels in the same chip.

The TGC attenuator output is AC-coupled into the PGA. PGA gain is programmed through the two gain bits (PG0 and PG1) in the SPI control register, and can be configured to four different gain settings of 23.5, 29, 34.5 and 40 dB .

The AAF is a third-order Butterworth low-pass filter. The au-to-tracking cutoff frequency is typically one-third of the sampling frequency, and is typically triggered by the FLEX command calibration. There are control bits in SPI for adjusting the auto-tracking cutoff frequency up to $\pm 15 \%$ of the typical value for the anti-aliasing filter. In addition, the SPI control register AAF bits can set more frequency range options.

The ADC converters in the MD3872 use a very low power, high-speed, self-calibrated pipeline architecture that moves the samples through the pipeline stages every half clockcycle. The converted digital results are serialized and sent through the LVDS output drivers. The total latency is $5.5 \mathrm{in}-$ put clock cycles.

The following sections are detail descriptions of each programmable feature.

## LNA Gain \& Active Impedance Matching

The LNA consists of a differential voltage gain low noise amplifier. The LNA's inverting single-ended output gain is $A=$ 4.0 and $A=2.5$ when the LNA differential gain is 18 dB and 14 dB , respectively. With a known fixed gain, a feedback resistor can be connected between the LNA positive input pin (IN1+) and the inverting output pin (PA1-), and in series with a capacitor. This technique is well known as active termination and results in a better noise figure (NF) than passive termination. The effective input resistance is RIN = RFB/ (1+A). In addition, the MD3872 provides a dual mode feed-
back resistor option for connecting two feedback resistors in parallel through the SWx pins. The SWx pin is connected to the PAx pin with an internal switch which is controlled by the SWLNA bit in SPI.

## TGC / CW Mode \& Power Consumption

At power up, all the SPI register's data bits are reset to 0 , and the MD3872 will go into the default: all TGC mode and the whole chip's current consumption is approximately 760 mW if the sampling clock is 40 MHz . When in the default state, $\mathrm{CW} / \overline{\mathrm{TGC}}=0,\left(\mathrm{ADDR}=6, \mathrm{D}[7: 0]={ }^{\prime} 00000000\right.$ ' $)$, ADCPD[7:0] ='00000000', all channels of LNA, VGA, AAF and ADC are turned on. At the same time, PLL and LVDS will be turned on in this mode.

To control each TGC (LNA+VGA+AAF) channel individually, ADDR $=6$, CHOFF[7:0] provides selection of turning ON/ OFF for each TGC channel. For example, when MD3872 is in TGC mode, CW/TGC $=0$ and CHOFF[7:0] = '01111111', only the TGC channel 8 is switched ON and other channels are switched OFF. In this condition, the whole chip's current consumption will be quite a bit less than when all channels are ON. To power off each ADC individually in TGC mode, ADDR $=9$, ADCPD[7:0] can be programmed to state1. For example, ADCPD[7:0] = '10000000', ADC8 is powered down and the others are powered on. Note that in TGC mode, ADDR $=2,3,4$ and 5 are meaningless.

If $\mathrm{CW} / \overline{\mathrm{TGC}}=1$, MD3872 will go into CW mode, all the VGA, ADC, AFF, LVDS and PLL will be shut down automatically and $A D D R=6, D[7: 0]$ is meaningless. In CW mode, each channel's CW trans-conductance amplifiers ON and OFF are controlled by ADDR $=2,3,4$ and 5 as shown in the CW cross-point switch control register table. For example, if CW/ $\overline{\mathrm{TGC}}=1$, ADDR 2, D[11:0] ='100000100000', the MD3872 will be in CW mode and CW channels 1 and 2 will be turned on. At that time, LNA1 and LNA2 and CW-SW circuits will turn on, and the total CW output current coming from the channel 1 and channel 2 trans-conductance amplifiers will be differentially mixed into CW1+ and CW1-. The VDD current is about 25 mA increasing per CW channel. If setting ADDR $=2$ to 5 to CW mode ON state, all the LNA and CW trans-conductance amplifiers are switched ON.

## Anti-Aliasing Filter

The MD3872 provides two options for setting the AAF corner frequency in TGC mode. The first option is the sampling frequency tracking method in which the corner frequency is tracked with $1 / 3$ of the sampling frequency. It is achieved by the built-in six-bit resolution programmable RC value analog anti-aliasing filter for tracking with sampling frequency, temperature and process corner. It is enabled by CTL $=0$ and

FLEX bit/pin. The second option is the direct control method in which the corner frequency is set by directly programming the first four bits of the six-bit resolution. It is enabled by CTL $=1$. However, in this mode, the corner frequency is not tracked with temperature and process. The tolerance can be up to $+/-20 \%$. It is the easier method, as there is no need to trigger the FLEX pin/bit periodically. The direct control method is recommended if the application can tolerate a higher variation of the TGC bandwidth.

In sampling frequency tracking mode (CTL = 0), the ADDR = 7, D5 is FLEX to control the built-in AAF auto-tracking function. It is used only in TGC mode in which the AAF circuit is in operation. This SPI bit has the same function as the external FLEX pin. Either setting the SPI FLEX bit or setting the external pin can enable the AAF auto-tracking operation. If FLEX $=1$, the auto-tracking circuit will function and the AAF corner frequency will track with the external sampling clock. The tacking lock-in process time is less than $50 \mu \mathrm{~s}$. The tracking program will keep on generating a new six-bit code in each cycle for all the analog filters. Thus, it needs to set FLEX back to 0 if the programming operation is completed for the whole ultrasound system, otherwise, it will generate extra noise for the chip, and therefore precautions need to be applied. Before enabling this mode, the ADDR = 7, AAF[1:0] and ADDR $=8$, AAF[5:2] should be programmed first. The default state of AAF[1:0] sets the resultant tracking value to $100 \%$ of the $1 / 3$ of the sampling frequency. As in some applications, it may need a around $15 \%$ higher or $15 \%$ lower of the $1 / 3$ of the sampling frequency value or another more precise offset lower value (controlled by AAF[5:2]) with respect to the $1 / 3$ sampling frequency to achieve an appropriate TGC bandwidth for better noise performance. The AAF[5:0] control bits descriptions are shown in the AAF control table.

In the direct control method (CTL = 1), ADDR = 8, D[8:5] is $\operatorname{PR}[5: 2]$ to directly program the code for setting the AAF corner frequency as shown in the cut-off frequency direct control table. For example, if the signal tone is 3.0 MHz and the application needs the lowest AAF corner frequency for the lowest noise bandwidth such that the SNR will be the highest, the $\operatorname{PR}[5: 2]$ should be set to ' 1111 '.

The ADDR $=7$, D3 and D2 are SWLNA and GAINLNA to control the LNA feedback resistor switch and LNA gain as shown in data sheet SPI register table's notes-6 and -7. These bits will affect both TGC mode and CW mode. The feedback resistor switch option is for re-matching the input impendence externally if the LNA gain is changed. The ADDR = 7, D1 and D0 are PG[1:0] for the gain settings of VGA.

## ADC Clock and PLL

ADC is the eight-channel analog to digital converter and is driven by the ADC sampling-frequency clock CLK+/CLKLVDS input pair which normally operates from a low-jitter external 20 to 40 MHz LVDS clock source. The built-in PLL phase-locked loop circuit will provide six times the input frequency as the DCLK serial data bit clock and a phase shifted version with the same frequency as the FCLK data-frame clock. The PLL also provides the ADC internal switching and conversion clocks. It is highly recommended routing the CLK+/CLK- input trace as a well controlled impedance differential LVDS line-pair, with a $100 \Omega$ resistor as termination resistor right at the device CLK pins.

## LVDS Data Alignment Pattern

There are two 12-bit digital output test binary pattern registers TPD1[11:0] and TPDC[11:0] available that can be programmed through the SPI. The SPI control register bit ATP[1:0] selects which pattern or data of ADC results to provide to the LVDS data output. These patterns allow the user to perform timing alignment adjustments among the ADCLK and LCLK, and output data.

## LVDS Outputs and Clock Timing \& Delay Adjustment

The differential outputs conform to a low power, reduced signal option of the ANSI-644 standard. The LVDS outputs are designed for interfacing with LVDS receivers in custom ASICs or FPGAs that have LVDS capability up to 480 MB/ sec with a $100 \Omega$ termination resistor placed as close to the receiver as possible. It is recommended that the trace length be no longer than 12 inches and that the differential output traces be kept close together and at equal lengths.

The format of the output data is offset binary by default. An example of the output coding format can be found in the table above. Two output clocks are provided to assist in capturing data from the MD3872. DCLK $\pm$ is used to clock the output data and is equal to six times the sampling clock rate. Data is clocked out of the MD3872 and must be captured on the rising and falling edges of the CLK $\pm$ that supports double data rate (DDR) capturing. The frame clock output, $C L K \pm$ is used to signal the start of a new output byte and is equal to the sampling clock rate. In addition, MD3872 provides LVDS ADC data OUT, FCLK and DCLK output time-delay and swing amplitude adjustment bits in SPI registers OUTDLY, FDDLY, SETP and SWING. For detailed timing, see the timing diagram and tables above.

## CW Cross-point Switch and Control

MD3872 consists of an 8x8 CW cross-point switch matrix. There are eight differential inputs and eight differential outputs in the matrix. The differential inputs come from the outputs of a differential transconductance amplifier which is driven by the LNA directly. There are 16 output pins for the eight differential outputs. The outputs of the transconductance amplifier are current outputs, which can be easily routed via switches and perform summing operations for the CWD beamforming function. In single-end mode, only non-inverting transconductance amplifier output current is switched to the selected CW single-ended output. Inverting transconductance amplifier output current is disabled in this mode. All the cross-point switches in the CW switch matrix can be programmed individually through the SPI control interface. The whole CW mode operation occupies four registers in the SPI interface registers map.

## Power-Down Mode

The ADDR = 7, D6 is the PDC bit to control where the LNA, CW-SW, VGA, AFF programmable reference current originates. If PDC $=0$, the current usage of all four front-end circuits will be referenced from the internal front-end circuit current reference. Note that this circuit will not affect the current usage of PLL, ADC and LVDS circuit. If $\operatorname{PDC}=1$, the front-end circuits will refer to the external resistor current. In normal operation, it is strongly recommended that the internal reference be used, as it is optimized for the balance of front-end circuits' performance and power consumption. If a $10 \%$ reduction in current is desired, set PDC $=1$ and connect an external bias resistor from EBC to GND. This will sacrifice a certain amount of performance.Thus, if PDC $=1$ and no external resistor is connected to the EBC pin (N.C.), the total current consumption will be decreased to almost no referenced current state.


Fig. 1. MD3872 vs Competitor @1.4MHz


Fig. 3. MD3872 vs Competitor @5.0MHz


Fig. 2. MD3872 vs Competitor @1.4MHz


Fig. 4. MD3872 vs Competitor @7.0MHz

## Note:

Green: sine wave input to MD3872 on the evaluation board
Blue: some sine wave input to competitor on the evaluation board
Both at $f_{s}=40 \mathrm{MHz}, L N A R F B=250 \Omega$, Gain $=18 \mathrm{~dB}, A A F=1 / 3 f_{\mathrm{s}}$
Sample data length 32768 points FFT with Blackman-Harris Windowing


Fig. 5 ADC Output Data Waveform and FFT


Fig. 6. Output-Referred Noise Histogram (with TGC $=0.3 \mathrm{~V}$ )


Fig. 8. Antialiasing Filter (AAF) Pass-Band Response, No HPF Applied


Fig. 7. Output-Referred Noise Histogram (with TGC = 1.3V)


Fig. 9. Channel High-Pass Filter (HPF) Corner Frequency Response


Fig. 10. Typical IMD2 and IMD3 Performance


Fig. 12. SNR and SINAD vs. TGC Volatge

Fig. 14. SNRFS vs. Sampling Frequency


Fig. 11. Gain Error vs. TGC Voltage (at $25^{\circ} \mathrm{C} @ \mathrm{fs}=50 \mathrm{MHz}, \mathrm{AAF} \mathrm{fs} / 3$ )


Fig. 13. HD2 \& HD3 vs. Sampling Frequency


Fig. 15. SFDR vs. Sampling Frequency

## Equivalent Circuits



Fig. 16 Equivalent LNA Input Circuit


Fig. 18 Equivalent Clock Input Circuit


Fig. 20 Equivalent SDO Output Circuit


Fig. 22 Equivalent SCK Input Circuit


Fig. 17 Equivalent LNA Output Circuit


Fig. 19 Equivalent SDI Output Circuit


Fig. 21 Equivalent Digital Output Circuit


Fig. 23 Equivalent RBIAS Circuit

## Equivalent Circuits (cont.)



Fig. 24 Equivalent CSB Input Circuit


Fig. 26 Equivalent VREF Circuit


Fig. 28 Equivalent CW Output Circuit


Fig. 25 Equivalent EXT Input Circuit


Fig. 27 Equivalent TGC Input Circuit

## Pin Description

| Pin | Designator | Description |
| :---: | :---: | :---: |
| 1 | GND | Ground |
| 2 | AVDD2 | Supply for ADC (1.8V) |
| 3 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 4 | SW5 | Channel 5 LNA Output Complement |
| 5 | PA5- | Channel 5 LNA Negative Output |
| 6 | IN5+ | Input Channel 5 |
| 7 | CM5 | Channel 5 Common-mode decoupling, bypass to ground |
| 8 | IN5- | Complementary Input Channel 5 |
| 9 | AVDD2 | Supply for ADC (1.8V) |
| 10 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 11 | SW6 | Channel 6 LNA Output Complement |
| 12 | PA6- | Channel 6 LNA Negative Output |
| 13 | IN6+ | Input Channel 6 |
| 14 | CM6 | Channel 6 Common-mode decoupling, bypass to ground |
| 15 | IN6- | Complementary Input Channel 6 |
| 16 | AVDD2 | Supply for ADC (1.8V) |
| 17 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 18 | SW7 | Channel 7 LNA Output Complement |
| 19 | PA7- | Channel 7 LNA Negative Output |
| 20 | IN7+ | Input Channel 7 |
| 21 | CM7 | Channel 7 Common-mode decoupling, bypass to ground |
| 22 | IN7- | Complementary Input Channel 7 |
| 23 | AVDD2 | Supply for ADC (1.8V) |
| 24 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 25 | SW8 | Channel 8 LNA Output Complement |
| 26 | PA8- | Channel 8 LNA Negative Output |
| 27 | IN8+ | Input Channel 8 |
| 28 | CM8 | Channel 8 Common-mode decoupling, bypass to ground |
| 29 | IN8- | Complementary Input Channel 8 |
| 30 | GND | Ground |
| 31 | CLK- | Negative clock input pin |
| 32 | CLK+ | Positive clock input pin |
| 33 | AVDD4 | Supply for Clock distribution circuit (1.8V) |
| 34 | SDO | Serial Data Output |

Pin Description (cont.)

| Pin | Designator | Description |
| :---: | :---: | :---: |
| 35 | NC | Reserved, do not connect |
| 36 | AVDD5 | Supply for PLL (1.8V) |
| 37 | DVDD | Supply for LVDS (1.8V) |
| 38 | OUT8- | ADC LVDS output negative - Channel 8 |
| 39 | OUT8+ | ADC LVDS output positive - Channel 8 |
| 40 | OUT7- | ADC LVDS output negative - Channel 7 |
| 41 | OUT7+ | ADC LVDS output positive - Channel 7 |
| 42 | OUT6- | ADC LVDS output negative - Channel 6 |
| 43 | OUT6+ | ADC LVDS output positive - Channel 6 |
| 44 | OUT5- | ADC LVDS output negative - Channel 5 |
| 45 | OUT5+ | ADC LVDS output positive - Channel 5 |
| 46 | FCLK- | Negative LVDS frame clock output |
| 47 | FCLK+ | Positive LVDS frame clock output |
| 48 | DCLK- | Negative LVDS data clock |
| 49 | DCLK+ | Positive LVDS data clock |
| 50 | OUT4- | ADC LVDS output negative - Channel 4 |
| 51 | OUT4+ | ADC LVDS output positive - Channel 4 |
| 52 | OUT3- | ADC LVDS output negative - Channel 3 |
| 53 | OUT3+ | ADC LVDS output positive - Channel 3 |
| 54 | OUT2- | ADC LVDS output negative - Channel 2 |
| 55 | OUT2+ | ADC LVDS output positive - Channel 2 |
| 56 | OUT1- | ADC LVDS output negative - Channel 1 |
| 57 | OUT1+ | ADC LVDS output positive - Channel 1 |
| 58 | DVDD | Supply for LVDS (1.8V) |
| 59 | N.C | Reserved, do not connect |
| 60 | STBY | Standby |
| 61 | PDWN | Power down |
| 62 | AVDD6 | Supply for SPI (1.8V) |
| 63 | SCLK | Serial clock |
| 64 | SDI | Serial data input |
| 65 | CSB | Chip select bar |
| 66 | NC | Reserved, do not connect |
| 67 | NC | Reserved, do not connect |
| 68 | IN1- | Complementary Input Channel 1 |

Pin Description (cont.)

| Pin | Designator | Description |
| :---: | :---: | :---: |
| 69 | CM1 | Channel 1 Common-mode decoupling, bypass to ground |
| 70 | IN1+ | Input Channel 1 |
| 71 | PA1- | Channel 1 LNA Negative Output |
| 72 | SW1 | Channel 1 LNA Output Complement |
| 73 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 74 | AVDD2 | Supply for ADC (1.8V) |
| 75 | IN2- | Complementary Input Channel 2 |
| 76 | CM2 | Channel 2 Common-mode decoupling, bypass to ground |
| 77 | IN2+ | Input Channel 2 |
| 78 | PA2- | Channel 2 LNA Negative Output |
| 79 | SW2 | Channel 2 LNA Output Complement |
| 80 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 81 | AVDD2 | Supply for ADC (1.8V) |
| 82 | IN3- | Complementary Input Channel 3 |
| 83 | CM3 | Channel 3 Common-mode decoupling, bypass to ground |
| 84 | IN3+ | Input Channel 3 |
| 85 | PA3- | Channel 3 LNA Negative Output |
| 86 | SW3 | Channel 3 LNA Output Complement |
| 87 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 88 | AVDD2 | Supply for ADC (1.8V) |
| 89 | IN4- | Complementary Input Channel 4 |
| 90 | CM4 | Channel 4 Common-mode decoupling, bypass to ground |
| 91 | IN4+ | Input Channel 4 |
| 92 | PA4- | Channel 4 LNA Negative Output |
| 93 | SW4 | Channel 4 LNA Output Complement |
| 94 | AVDD1 | Supply for LNA \& VGA (1.8V) |
| 95 | AVDD2 | Supply for ADC (1.8V) |
| 96 | GND | Ground |
| 97 | GND | Ground |
| 98 | FLEX | Enable automatic low-pass tuning $1=0$ on, $0=$ off (default) |
| 99 | AVDD7 | Supply for auto-tuning circuit (1.8V) |
| 100 | CW1+ | CW Switch Output |
| 101 | CW1- | CW Switch Output |
| 102 | CW2+ | CW Switch Output |

## Pin Description (cont.)

| Pin | Designator | Description |
| :---: | :---: | :---: |
| 103 | CW2- | CW Switch Output |
| 104 | CW3+ | CW Switch Output |
| 105 | CW3- | CW Switch Output |
| 106 | CW4+ | CW Switch Output |
| 107 | CW4- | CW Switch Output |
| 108 | CVDD | CW VDD (3.3V) |
| 109 | RBIAS | Bias Setting Resistor ( $50 \mathrm{k} \Omega$ to GND) |
| 110 | EXT | Internal/external reference select, $\mathrm{Hi}=$ External reference is selected |
| 111 | VREF | Supply (1.0V) |
| 112 | REF- | Differential reference (-), external decoupling capacitors $0.1 \mu \mathrm{~F} / / 10 \mu \mathrm{~F}$ to REF+, and $0.1 \mu \mathrm{~F}$ to GND |
| 113 | REF+ | Differential reference (+), external decoupling capacitors $0.1 \mu \mathrm{~F} / / 10 \mu \mathrm{~F}$ to REF-, and $0.1 \mu \mathrm{~F}$ to GND |
| 114 | AVDD3 | Supply for ADC reference circuit (1.8V) |
| 115 | CVDD | CW VDD 3.3V |
| 116 | CW5+ | CW Switch Output |
| 117 | CW5- | CW Switch Output |
| 118 | CW6+ | CW Switch Output |
| 119 | CW6- | CW Switch Output |
| 120 | CW7+ | CW Switch Output |
| 121 | CW7- | CW Switch Output |
| 122 | CW8+ | CW Switch Output |
| 123 | CW8- | CW Switch Output |
| 124 | AVDD0 | Supply for LNA \& VGA bias (1.8V) |
| 125 | TGC | TGC attenuator control input for all channel, 0 to 1.8 V |
| 126 | GSC | TGC optional slope adjustment voltage input. |
| 127 | CM0 | Common-mode decoupling, bypass to ground |
| 128 | EBC | External Current Bias, Do not connect |
| Thermal Slug | GND | Thermal Slug must externally connect to the RF ground and PCB heat sink |

## 128-Lead TQFP (w/Heat Slug) Package Outline (HF)

## $14.00 \times 14.00 \mathrm{~mm}$ body, 1.20 mm height (max), 0.40 mm pitch



Side View


View B

## Note:

1. A Pin 1 identifier must be located in the index area indicated. The Pin 1 identifier can be: a molded mark/identifier; an embedded metal marker; or a printed indicator.

| Symbol |  | A | A1 | A2 | b | D | D1 | D2 | E | E1 | E2 | e | L | L1 | L2 | $\boldsymbol{\theta}$ | 01 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Dimension (mm) | MIN | - | 0.05 | 0.95 | 0.13 | $\begin{aligned} & 16.00 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 14.00 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 9.50 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 16.00 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 14.00 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 9.50 \\ & \text { BSC } \end{aligned}$ | $\begin{aligned} & 0.40 \\ & \text { BSC } \end{aligned}$ | 0.45 | $\begin{aligned} & 1.00 \\ & \text { REF } \end{aligned}$ | $\begin{aligned} & 0.25 \\ & \text { BSC } \end{aligned}$ | $0^{\circ}$ | $11^{\circ}$ |
|  | NOM | - | - | 1.00 | 0.18 |  |  |  |  |  |  |  | 0.60 |  |  | $3.5{ }^{\circ}$ | $12^{\circ}$ |
|  | MAX | 1.20 | 0.15 | 1.05 | 0.23 |  |  |  |  |  |  |  | 0.75 |  |  | $7{ }^{\circ}$ | $13^{\circ}$ |

## Drawings not to scale

Supertex Doc. \#: DSPD-128TQFPHF, Version NR011713.
(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to http://www.supertex.com/packaging.html.)

[^0]
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