HF series

Proportional multi-axis fingertip controllers • non-contacting Hall effect technology

DISTINCTIVE FEATURES

One, two or three axis
Analog outputs
CAN bus J1939 and CANopen options
USB 2.0 HID interface options
Connectorized housing

ENVIRONMENTAL SPECIFICATIONS

• Operating Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
• Storage Temperature: -40 °C to +85 °C (-40 °F to +185 °F)
• Above Panel Sealing: Up to IP67 (subject to final specifications)
• EMC Immunity Level (V/M): EN61000-4-3
• EMC Emissions Level: EN61000-6-3:2001
• ESD: EN61000-4-2
• Output linearity: ±200 mV
• Dual output interlinearity (X/Y): ±400 mV
• Dual output interlinearity (Z): ±600 mV

SENSOR SPECIFICATIONS

• Sensor: Hall effect, single or dual
• Supply Voltage Range: 5 VDC ±0.01 VDC
• Supply Current: 40 mA typical / 50 mA max (3 axis)
• Reverse Polarity Max: -10 VDC
• Transient Overvoltage Max: 16 VDC
• Ratiometric Output Voltage: see output options
• Output Current: 8 mA
• Output Load: 1 K ohm min
• Output Impedance: 2 Ω

MATERIALS

• Shaft: Stainless Steel
• Boot: Silicone
• Handles: Glass filled nylon*
• Body: Glass filled nylon

The company reserves the right to change specifications without notice.
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**TERMINATION (ANALOG OUTPUTS ONLY)**

- The HF series (Output options 0-11) features a Hirose DF11-12DP-2DS9 (24) header (male receptacle) (Fig 1)
- The mating harness is not included but may be specified at the time of order. Contact your APEM sales representative. This optional harness features a Hirose DF11-12DS-2C connector (female socket)(Fig. 2) to individual stripped and tinned wire leads.
- Header specifications: 12 position, 2mm pitch dual row (2x6) pin header
- Wire harness specifications: 22AWG Teflon, 25cm multi-conductor with heat shrink. Hirose DF11-12DS-2C to stripped and tinned wire leads

**MECHANICAL SPECIFICATIONS**

**X/Y AXIS**
- Break Out Force: 1.3 N (0.3 lbf)
- Operating Force: 2.8 N (0.63 lbf)
- Deflection Angle: 36° (±18° from center)
- Expected Mechanical Life: 5 million lifecycles
- Lever Action: Single spring, omnidirectional

**Z AXIS**
- Break Out Torque: 0.09 Nm (0.80 lbf in)
- Operating Torque: 0.121 Nm (1.07 lbf in)
- Degrees of rotation: 60° (30° from center)
- Expected Mechanical Life: 5 million lifecycles
- Handle Action: Spring centering

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* Most handles, dependent upon configurations

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**JOYSTICK HEADER - HIROSE DF11-12DP-2DS9 (24) PINOUT (FIG 1)**

<table>
<thead>
<tr>
<th>PIN 2</th>
<th>PIN 4</th>
<th>PIN 6</th>
<th>PIN 8</th>
<th>PIN 10</th>
<th>PIN 12</th>
</tr>
</thead>
<tbody>
<tr>
<td>RED</td>
<td>BLUE</td>
<td>YELLOW</td>
<td>GREEN</td>
<td>WHITE</td>
<td>--</td>
</tr>
<tr>
<td>BLACK</td>
<td>BLU/WHT</td>
<td>YEL/BLK</td>
<td>GRN/BLK</td>
<td>ORANGE</td>
<td>VIOLET</td>
</tr>
</tbody>
</table>

**MATING WIRE HARNESS COLOR DEFINITION (FIG 2)**

<table>
<thead>
<tr>
<th>HIROSE DF11-12DS-2C CONNECTOR PIN #</th>
<th>WIRE COLOR</th>
<th>JOYSTICK FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Black</td>
<td>Ground</td>
</tr>
<tr>
<td>2</td>
<td>Red</td>
<td>Supply power</td>
</tr>
<tr>
<td>3</td>
<td>Blue / white</td>
<td>X axis (dual output)</td>
</tr>
<tr>
<td>4</td>
<td>Blue</td>
<td>X axis</td>
</tr>
<tr>
<td>5</td>
<td>Yellow / black</td>
<td>Y axis (dual output)</td>
</tr>
<tr>
<td>6</td>
<td>Yellow</td>
<td>Y axis</td>
</tr>
<tr>
<td>7</td>
<td>Green / black</td>
<td>Z axis (dual output)</td>
</tr>
<tr>
<td>8</td>
<td>Green</td>
<td>Z axis</td>
</tr>
<tr>
<td>9</td>
<td>Orange</td>
<td>Button one</td>
</tr>
<tr>
<td>10</td>
<td>White</td>
<td>Button common</td>
</tr>
<tr>
<td>11</td>
<td>Violet</td>
<td>Button two</td>
</tr>
<tr>
<td>12</td>
<td>--</td>
<td>--</td>
</tr>
</tbody>
</table>
**HF series**

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**GENERAL MOUNTING OPTIONS**

**DROP-IN MOUNT**

- 4-40 x 9/16 Phil Panhead
- Brass insert 4 places
- 23.83 (0.938)

**REAR MOUNT**

- 4-40 x 3/8 Phil Panhead
- Brass insert 4 places
- 30.05 (1.183)

**PANEL CUT-OUT**

**DROP-IN MOUNT**

- Ø41.28 (1.625)
- Ø3.18 x 4 places
- 35.56 (1.40)
- 35.56 (1.40)

**REAR MOUNT**

- Ø41.91 (1.650)
- Ø3.18 x 4 places
- 35.56 (1.40)
- 35.56 (1.40)

**CLAMPING RING**

- 35.56 (1.40)
- 48.26 (1.90)
- 48.26 (1.90)
- 7.10 (0.28)

**AXIS ORIENTATION**

**NOTES:**

- For DROP-IN mounting, panel thickness can be 1.17 mm to 3.17 mm (0.046 in to 0.125 in).
- For REAR MOUNT, the maximum panel thickness is 1.6 mm (0.063 in).
- A panel thickness of 1/16” (1.6 mm/0.063 in) was considered for all below panel depth values.
- The below panel depth is extended by 7.11 mm (0.28 in) with the USB, Cursor Emulation, Voltage Regulator options.
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CAN J1939 INTERFACE SPECIFICATION

The HF Series joystick can be configured with a maximum of three axes and two buttons. All axis and button data are delivered on a CAN 2.0B compliant physical interface. Two additional signals allow configuration of the controller Source Address. Controller messages are delivered per the SAE J1939-71 message protocol.

CAN 2.0B INTERFACE PARAMETERS

• Baud rate: 250 kbps
• Transmission repetition rate: 50ms
• BJM1/EJM1 interval time: 20ms
• Terminating resistor: No
(available by special request to factory)

CAN MESSAGE PROTOCOL

• Primary Axis and button data on Basic Joystick Message 1 (BJM1):
  - Priority: 3
  - Base PGN: 0xFD06
  - Source address: 0x13
  - Data field: 8 bytes

• Z-Axis data on Extended Joystick Message 1 (EJM1):
  - Priority: 3
  - Base PGN: 0xFD07
  - Source address: 0x13
  - Data field: 8 bytes

CAN MESSAGE ADDRESSES

Alternate source addresses may be selected by grounding combinations of the blue and/or orange wires. For further information, please see TERMINATION on page 6.

<table>
<thead>
<tr>
<th>CAN SOURCE ADDRESS</th>
<th>ORANGE WIRE</th>
<th>BLUE WIRE</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x13 (default)</td>
<td>OPEN</td>
<td>OPEN</td>
</tr>
<tr>
<td>0x23</td>
<td>OPEN</td>
<td>Grounded</td>
</tr>
<tr>
<td>0x33</td>
<td>Grounded</td>
<td>OPEN</td>
</tr>
<tr>
<td>0x43</td>
<td>Grounded</td>
<td>Grounded</td>
</tr>
</tbody>
</table>

BJM1 DATA FIELD STRUCTURE:

<table>
<thead>
<tr>
<th>START POSITION (BYTE/BIT)</th>
<th>LENGTH (BITS)</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1/1</td>
<td>2</td>
<td>Primary X-axis neutral position status</td>
</tr>
<tr>
<td>1/3</td>
<td>2</td>
<td>Primary X-axis left position status</td>
</tr>
<tr>
<td>1/5</td>
<td>2</td>
<td>Primary X-axis right position status</td>
</tr>
<tr>
<td>1/7 to 2/8</td>
<td>10</td>
<td>Primary X-axis position data</td>
</tr>
<tr>
<td>3/1</td>
<td>2</td>
<td>Primary Y-axis neutral position status</td>
</tr>
<tr>
<td>3/3</td>
<td>2</td>
<td>Primary Y-axis down position status</td>
</tr>
<tr>
<td>3/5</td>
<td>2</td>
<td>Primary Y-axis up position status</td>
</tr>
<tr>
<td>3/7 to 4/8</td>
<td>10</td>
<td>Primary Y-axis position data</td>
</tr>
<tr>
<td>6/5</td>
<td>2</td>
<td>Button 2 status</td>
</tr>
<tr>
<td>6/7</td>
<td>2</td>
<td>Button 1 status</td>
</tr>
</tbody>
</table>

EJM1 DATA FIELD STRUCTURE:

<table>
<thead>
<tr>
<th>START POSITION (BYTE/BIT)</th>
<th>LENGTH (BITS)</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>5/1</td>
<td>2</td>
<td>Primary Z-axis neutral position status</td>
</tr>
<tr>
<td>5/3</td>
<td>2</td>
<td>Primary Z-axis counter-clockwise position status</td>
</tr>
<tr>
<td>5/5</td>
<td>2</td>
<td>Primary Z-axis clockwise position status</td>
</tr>
<tr>
<td>5/7 TO 4/8</td>
<td>10</td>
<td>Primary Z-axis position data</td>
</tr>
</tbody>
</table>

CUSTOM CAN BUS J1939 FIRMWARE*

• Baud rate: 125 kbps, 500 kbps, 1Mbps (250 kbps default)
• Custom CAN addresses
• Custom CAN bus output

* Custom CAN bus firmware available upon request.
CANOPEN INTERFACE SPECIFICATION

CANOPEN INTERFACE PARAMETERS*

- Baud rate: 250 kbps
- Node ID: 20h
- Buttons: 1A0H (180H + NODE ID)
- Analog (axis) outputs: 2A0h (280h + Node ID)
- Heartbeat (500ms): 720h (700h + Node ID)
- Axis resolution: 8 bit
- Network Management: Auto start enabled

CANOPEN NODE ID SELECTION

Alternate NODE IDs may be selected by grounding the blue and/or orange wires. For further information, please see TERMINATION on page 6.

<table>
<thead>
<tr>
<th>NODE ID SELECT</th>
<th>ORANGE WIRE</th>
<th>BLUE WIRE</th>
</tr>
</thead>
<tbody>
<tr>
<td>20H (default)</td>
<td>OPEN</td>
<td>OPEN</td>
</tr>
<tr>
<td>21H</td>
<td>OPEN</td>
<td>Grounded</td>
</tr>
<tr>
<td>22H</td>
<td>Grounded</td>
<td>OPEN</td>
</tr>
<tr>
<td>23H</td>
<td>Grounded</td>
<td>Grounded</td>
</tr>
</tbody>
</table>

CANOPEN BUTTON OUTPUT CONFIGURATION

BUTTON STATUS IS TRANSMITTED IN THE ONE BYTE DATA FIELD OF FRAMES WITH AN IDENTIFIER OF 1A0 (DEFAULT)

<table>
<thead>
<tr>
<th>Identifier</th>
<th>Byte 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>1A0</td>
<td>Buttons (2:0)</td>
</tr>
</tbody>
</table>

CANOPEN ANALOG OUTPUT CONFIGURATION

EIGHT BIT ANALOG DATA IS TRANSMITTED IN THE THREE BYTE DATA FIELD OF FRAMES WITH AN IDENTIFIER OF 2A0 (DEFAULT)

<table>
<thead>
<tr>
<th>Identifier</th>
<th>Byte 0</th>
<th>Byte 1</th>
<th>Byte 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>2A0</td>
<td>A_IN0 (7:0)</td>
<td>A_IN1 (7:0)</td>
<td>A_IN2 (7:0)</td>
</tr>
</tbody>
</table>

CUSTOM CANOPEN Firmware*

- Baud rate: 125 kbps, 500 kbps, 1Mbps (250 kbps default)
- Custom Node IDs (default 20 hexadecimal)
- 10-bit axis resolution
- 12-bit axis resolution
- Signed resolution
- Custom CANopen output

* Custom CAN bus firmware available upon request.
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**TERMINATION (CAN OUTPUTS ONLY)**

- HF series joysticks configured with CAN outputs (Output options 2C and 3C only) feature a JST B6B-PH-S(LF)(SN) header (male receptacle) (Fig 1) and are supplied with a mating wire harness (Fig 2)
- Header specifications: JST B6B-PH-S(LF)(SN) - 6 position, 2mm pitch, single row header (Fig 1)
- Mating wire harness specifications: Six conductor, 22 AWG, 56 cm PTFE, JST PHR-6 to stripped and tinned wire leads (Fig 2)

**CANOPEN LSS INTERFACE SPECIFICATIONS**

The CANopen LSS interface option follows the CiA305 and CiA401 standards for CAN in automation. The node ID, baud rate and additional configurations can be set and stored in the EEPROM by Service Data Object. The default settings are as follows:

<table>
<thead>
<tr>
<th>SETTINGS</th>
<th>DEFAULT CONFIGURATION</th>
</tr>
</thead>
<tbody>
<tr>
<td>Baud rate</td>
<td>250 kbits/s</td>
</tr>
<tr>
<td>Node ID</td>
<td>20h</td>
</tr>
<tr>
<td>Analog (axis) outputs</td>
<td>2A0h (280h + Node ID)</td>
</tr>
<tr>
<td>Buttons</td>
<td>1A0h (180h + Node ID)</td>
</tr>
<tr>
<td>Heartbeat (500ms)</td>
<td>720h (700h + Node ID)</td>
</tr>
<tr>
<td>Axis Resolution</td>
<td>Unsigned 10-bit</td>
</tr>
</tbody>
</table>

**CAN BUS SPECIFICATIONS**

**DIMENSIONS**

**HEADER PINOUT AND MATING WIRE HARNESS COLOR DEFINITION**

<table>
<thead>
<tr>
<th>HEADER PINOUT</th>
<th>MATING WIRE HARNESS</th>
</tr>
</thead>
<tbody>
<tr>
<td>JST B6B-PH- S(LF)(SN) HEADER PIN #</td>
<td>CAN BUS FUNCTION</td>
</tr>
<tr>
<td>1</td>
<td>Supply power (7 to 35 VDC)</td>
</tr>
<tr>
<td>2</td>
<td>Ground</td>
</tr>
<tr>
<td>3</td>
<td>ID select MSB</td>
</tr>
<tr>
<td>4</td>
<td>ID select LSB</td>
</tr>
<tr>
<td>5</td>
<td>CAN Hi</td>
</tr>
<tr>
<td>6</td>
<td>CAN Lo</td>
</tr>
</tbody>
</table>

* Custom CAN bus firmware available upon request.
**PROPORTIONAL MULTI-AXIS FINGERTIP CONTROLLERS**

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**USB SPECIFICATIONS**

- Supply Voltage Range: 5.00 VDC
- Maximum current: 70 mA
- USB version: 2.0

**USB GAME CONTROLLER**

Featuring USB 2.0 HID compliant interface, APEM’s USB joysticks are recognized as standard HID “game controller” devices. Adhering to the HID specification, APEM’s USB joysticks are plug-and-play with most versions of Windows. Joystick button and axis assignments are dependent upon the controlled application.

**Features**

- USB 2.0 HID compliant “game controller” device
- Easy to install and operate
- Functions determined by controlled application
- 12-bit (0 to 4095) axis resolution

**Termination (supplied cable)**

- USB Male Type A Connector (198 cm)
  - (72" +/-1") - overmolded cabled - Mini B to Male Type A USB connector (option 0U)
  - (84" +/-1") - overmolded cable - Male Type A USB connector (option 2U)

---

**USB CURSOR EMULATION**

The Cursor Emulation option converts multi-axis joystick output into a mouse or cursor control device. The Cursor Emulation option is ideal for vehicle applications subjected to dirt and high vibration which makes operating a traditional cursor control device difficult. Cursor simulation is only compatible with Window OS.

**Features**

- HID compliant “mouse” device

**Button Function**

- B1: Left Mouse Click
- B2: Right Mouse Click

**Termination (supplied cable)**

- USB Male Type A Connector (185 cm):
  - (72" +/-1") - overmolded cabled - Mini B to Male Type A USB connector (option 0U)

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**SUPPORTED OPERATING SYSTEMS: USB GAME CONTROLLER AND CURSOR EMULATION**

**Windows Operating System**

- Windows 7
- Windows 8.1
- Windows 10

**Linux Operating System**

APEM’s USB joysticks are compatible with Linux, although system compatibility is not guaranteed. The user is responsible for verifying specific Linux OS compatibility.

**Custom Firmware**

Custom configurations and firmware is available upon request. Available options include:

- 8-bit axis resolution
- 10-bit axis resolution
- Signed bit axis resolution
- Custom USB product name

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**VOLTAGE REGULATOR SPECIFICATIONS**

The Voltage Regulator allows APEM’s Hall effect joysticks to operate with a range of supply voltages.

**Voltage Regulator - Unipolar**

- Supply Voltage Range: 8-35 VDC
- Output Voltage Range: see output options
- Maximum Current: 90 mA

**Voltage Regulator - Bipolar**

- Supply Voltage Range: 11-35 VDC
- Output Voltage Range: ±10 VDC
- Maximum Current: 90 mA

**Termination (supplied cable)**

- 28 AWG 20.32 cm (8.0") ±1.54 cm (1") PTFE
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## BUILD YOUR PART NUMBER

<table>
<thead>
<tr>
<th>SERIES</th>
<th>HANDLE</th>
<th>LIMITER PLATE</th>
<th>MOUNTING</th>
<th>OUTPUT OPTIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>HF</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>HANDLE</th>
<th>LIMITER PLATE</th>
<th>MOUNTING</th>
<th>OUTPUT OPTIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 Ball tip (2 axis)</td>
<td>S Square</td>
<td>1 Drop-in</td>
<td>0 0V-5V</td>
</tr>
<tr>
<td>11 Tapered (2 axis)</td>
<td>R Round</td>
<td>1 4 0V-5V-4.5V</td>
<td></td>
</tr>
<tr>
<td>22 1 Pushbutton (2 axis)</td>
<td>X Slotted</td>
<td></td>
<td>2 0.25V-4.75V</td>
</tr>
<tr>
<td>27 1 Pushbutton (2 axis), IP67 sealed</td>
<td>Y Slotted</td>
<td></td>
<td>3 1V-4V</td>
</tr>
<tr>
<td>33 3 Axis</td>
<td>P Plus</td>
<td></td>
<td>4 0V to 5V - Sensor 1 0V to 5V - Sensor 2</td>
</tr>
<tr>
<td>44 1 Pushbutton (3 axis)</td>
<td>C Cross</td>
<td></td>
<td>5 0.5V to 4.5V - Sensor 1 0.5V to 4.5V - Sensor 2</td>
</tr>
<tr>
<td>45 2 Pushbuttons (3 axis)</td>
<td>W Guided Feel Square</td>
<td></td>
<td>6 0.25V to 4.75V - Sensor 1 0.25V to 4.75V - Sensor 2</td>
</tr>
<tr>
<td>46 Low profile (3 axis)</td>
<td>Z Guided Feel Round</td>
<td></td>
<td>7 1V to 4V - Sensor 1 1V to 4V - Sensor 2</td>
</tr>
<tr>
<td>50 3 Axis, IP67 Sealed</td>
<td></td>
<td></td>
<td>8 0V to 5V - Sensor 1 5V to 0V - Sensor 2</td>
</tr>
<tr>
<td>51 3 Axis, 1 Pushbutton, IP67 sealed</td>
<td></td>
<td></td>
<td>9 0.5V to 4.5V - Sensor 1 4.5V to 0.5V - Sensor 2</td>
</tr>
<tr>
<td>52 3 Axis, 2 Pushbuttons, IP67 sealed</td>
<td></td>
<td></td>
<td>10 0.25V to 4.75V - Sensor 1 4.75V to 0.25V - Sensor 2</td>
</tr>
<tr>
<td>55 3 Axis, 2 Pushbuttons, IP67 sealed</td>
<td></td>
<td></td>
<td>11 1V to 4V - Sensor 1 4V to 1V - Sensor 2</td>
</tr>
</tbody>
</table>

1 Output voltage is ratiometric to supple voltage
2 Cable length is 6" ±1" side of joystick to Male Type A USB connector.
3 Cable length is 84" ±1" from bottom of joystick to Male Type A USB connector.
4 Requires operating voltage 7V ± 35V
5 Requires operating voltage 11V ± 35V
6, 7 & 8 Operating voltage: 7 - 35VDC
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HANDLE 33

HANDLE 44

HANDLE 45

HANDLE 46
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HANDLE 50

HANDLE 51

HANDLE 52

HANDLE 55