**DESCRIPTION**

The MP1540 is a 5-pin thin TSOT23 current mode step-up converter intended for small, low power applications. The MP1540 switches at 1.3MHz and allows the use of tiny, low cost capacitors and inductors 2mm or less in height. Internal soft-start results in small inrush current and extends battery life. The MP1540 operates from an input voltage as low as 2.5V and can generate 12V at up to 200mA from a 5V supply.

The MP1540 includes under voltage lockout, current limiting, and thermal overload protection to prevent damage in the event of an output overload. The MP1540 is available in a small 5-pin TSOT23 package.

**FEATURES**

- On Board Power MOSFET
- Uses Tiny Capacitors and Inductors
- 1.3MHz Fixed Switching Frequency
- Internal Soft-Start
- Operates with Input Voltage as Low as 2.5V and Output Voltage as High as 18V
- 12V at 200mA from 5V Input
- UVLO, Thermal Shutdown
- Internal Current Limit
- Available in a TSOT23-5 Package

**APPLICATIONS**

- Camera Phone Flash
- Handheld Computers and PDAs
- Digital Still and Video Cameras
- External Modems
- Small LCD Displays
- White LED Driver

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**TYPICAL APPLICATION**

![TYPICAL APPLICATION Diagram](image-url)
**PACKAGE REFERENCE**

![TOP VIEW](image)

**ABSOLUTE MAXIMUM RATINGS**

- **SW Pin**: –0.3V to +20V
- **All Other Pins**: –0.3V to +6.5V
- **Junction Temperature**: –40°C to +150°C
- **Lead Temperature**: –65°C to +260°C
- **Storage Temperature**: –65°C to +150°C

**Recommended Operating Conditions**

- **Supply Voltage** $V_{IN}$: 2.5V to 6V
- **Output Voltage** $V_{OUT}$: 3V to 18V
- **Operating Temperature**: –40°C to +85°C

**Thermal Resistance**

<table>
<thead>
<tr>
<th>Package</th>
<th>$\theta_{JA}$</th>
<th>$\theta_{JC}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>TSOT23-5</td>
<td>220°C/W</td>
<td>110°C/W</td>
</tr>
</tbody>
</table>

**Notes:**
1) Exceeding these ratings may damage the device.
2) The device is not guaranteed to function outside of its operating conditions.
3) Measured on approximately 1” square of 1 oz copper.

**ELECTRICAL CHARACTERISTICS**

$V_{IN} = V_{EN} = 5V$, $T_A = +25°C$ unless specified otherwise.

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Symbol</th>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Input Voltage</td>
<td>$V_{IN}$</td>
<td></td>
<td>2.5</td>
<td>6</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Under Voltage Lockout</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>Under Voltage Lockout Hysteresis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>Supply Current (Shutdown)</td>
<td>$V_{EN} = 0V$</td>
<td></td>
<td>0.1</td>
<td>1</td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>Supply Current (Quiescent)</td>
<td>$V_{FB} = 1.3V$</td>
<td></td>
<td>635</td>
<td>850</td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>Switching Frequency</td>
<td>$f_{SW}$</td>
<td></td>
<td>1.0</td>
<td>1.3</td>
<td>1.6</td>
<td>MHz</td>
</tr>
<tr>
<td>Maximum Duty Cycle</td>
<td>$V_{FB} = 0V$</td>
<td></td>
<td>80</td>
<td>85</td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>EN Threshold (Rising)</td>
<td>$V_{EN} = 0V$, $V_{IN} = 2.5V$</td>
<td></td>
<td>1.0</td>
<td>1.3</td>
<td>1.6</td>
<td>V</td>
</tr>
<tr>
<td>EN Threshold (Rising, $V_{IN} = 2.5V$)</td>
<td></td>
<td></td>
<td>1.1</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>EN Hysteresis</td>
<td></td>
<td></td>
<td>100</td>
<td></td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>EN Input Bias Current</td>
<td>$V_{FB} = 0V$, 6V</td>
<td></td>
<td>1</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>FB Voltage</td>
<td>$V_{FB}$</td>
<td></td>
<td>1.21</td>
<td>1.25</td>
<td>1.29</td>
<td>V</td>
</tr>
<tr>
<td>FB Input Bias Current</td>
<td>$V_{FB} = 1.25V$</td>
<td></td>
<td>–100</td>
<td>–30</td>
<td></td>
<td>nA</td>
</tr>
<tr>
<td>SW On-Resistance</td>
<td>$R_{DS(ON)}$</td>
<td></td>
<td>0.65</td>
<td></td>
<td></td>
<td>Ω</td>
</tr>
<tr>
<td>SW Current Limit</td>
<td></td>
<td></td>
<td>1.9</td>
<td></td>
<td></td>
<td>A</td>
</tr>
<tr>
<td>SW Leakage</td>
<td>$V_{SW} = 15V$</td>
<td></td>
<td>1</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>Thermal Shutdown</td>
<td></td>
<td></td>
<td>160</td>
<td></td>
<td></td>
<td>°C</td>
</tr>
</tbody>
</table>

**Notes:**
4) Guaranteed by design.
TYPICAL PERFORMANCE CHARACTERISTICS

\( V_{IN} = V_{EN} = 5V, \; T_A = +25^\circ C \) unless specified otherwise.

**Feedback Voltage vs Temperature**

**Frequency vs Temperature**

**Maximum Duty Cycle vs Temperature**

**Supply Current vs Temperature**

**RDS (ON) vs Input Voltage**

**Current Limit vs Duty Cycle**
PIN FUNCTIONS

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Name</th>
<th>Pin Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SW</td>
<td>Power Switch Output. SW is the drain of the internal MOSFET switch. Connect the power inductor and output rectifier to SW. SW can swing between GND and 20V.</td>
</tr>
<tr>
<td>2</td>
<td>GND</td>
<td>Ground.</td>
</tr>
<tr>
<td>3</td>
<td>FB</td>
<td>Feedback Input. FB voltage is 1.25V. Connect a resistor divider to FB.</td>
</tr>
<tr>
<td>4</td>
<td>EN</td>
<td>Regulator On/Off Control Input. A high input at EN turns on the converter, and a low input turns it off. When not used, connect EN to the input source for automatic startup. The EN pin cannot be left floating.</td>
</tr>
<tr>
<td>5</td>
<td>IN</td>
<td>Input Supply Pin. Must be locally bypassed.</td>
</tr>
</tbody>
</table>

OPERATION

The MP1540 uses a fixed frequency, peak current mode boost regulator architecture to regulate voltage at the feedback pin. The operation of the MP1540 can be understood by referring to the block diagram of Figure 1.

At the start of each oscillator cycle the MOSFET is turned on through the control circuitry. To prevent sub-harmonic oscillations at duty cycles greater than 50 percent, a stabilizing ramp is added to the output of the current sense amplifier and the result is fed into the negative input of the PWM comparator. When this voltage equals the output voltage of the error amplifier the power MOSFET is turned off.

The voltage at the output of the error amplifier is an amplified version of the difference between the 1.25V bandgap reference voltage and the feedback voltage. In this way the peak current level keeps the output in regulation. If the feedback voltage starts to drop, the output of the error amplifier increases. This results in more current to flow through the power MOSFET, thus increasing the power delivered to the output.

The MP1540 has internal soft start to limit the amount of input current at startup and to also limit the amount of overshoot on the output. The current limit is increased by a fourth every 40µs giving a total soft start time of 120µs.

Figure 1—Functional Block Diagram
APPLICATIONS INFORMATION

COMPONENT SELECTION

Setting the Output Voltage
Set the output voltage by selecting the resistive voltage divider ratio. Use 11.8kΩ for the low-side resistor R2 of the voltage divider.

\[
R_1 = \frac{R_2(V_{OUT} - V_{FB})}{V_{FB}}
\]

Where \( V_{OUT} \) is the output voltage and \( V_{FB} \) is the feedback voltage.

For \( R_2 = 11.8k\Omega \) and \( V_{FB} = 1.25V \), then

\[
R_1 (k\Omega) = 9.44k\Omega (V_{OUT} - 1.25V).
\]

Selecting the Input Capacitor
An input capacitor is required to supply the AC ripple current to the inductor, while limiting noise at the input source. This capacitor must have low ESR, so ceramic is the best choice.

Use an input capacitor value of 4.7µF or greater. This capacitor must be placed physically close to the IN pin. Since it reduces the voltage ripple seen at IN, it also reduces the amount of EMI passed back along that line to the other circuitry.

Selecting the Output Capacitor
A single 4.7µF to 10µF ceramic capacitor usually provides sufficient output capacitance for most applications. If larger amounts of capacitance are desired for improved line support and transient response, tantalum capacitors can be used in parallel with the ceramic. The impedance of the ceramic capacitor at the switching frequency is dominated by the capacitance, and so the output voltage ripple is mostly independent of the ESR. The output voltage ripple \( V_{RIPPLE} \) is calculated as:

\[
V_{RIPPLE} = \frac{I_{LOAD}(V_{OUT} - V_{IN})}{V_{OUT} \times C_2 \times f_{SW}}
\]

Where \( V_{IN} \) is the input voltage, \( I_{LOAD} \) is the load current, \( C_2 \) is the capacitance of the output capacitor, and \( f_{SW} \) is the 1.3MHz switching frequency.

Selecting the Inductor
The inductor is required to force the output voltage higher while being driven by the lower input voltage. Choose an inductor that does not saturate at the SW current limit. A good rule for determining the inductance is to allow the peak-to-peak ripple current to be approximately 30%-50% of the maximum input current. Make sure that the peak inductor current is below 75% of the typical current limit at the duty cycle used to prevent loss of regulation due to the current limit variation.

Calculate the required inductance value \( L \) using the equations:

\[
L = \frac{V_{IN}(V_{OUT} - V_{IN})}{V_{OUT} \times f_{SW} \times \Delta I}
\]

\[
I_{IN(MAX)} = \frac{V_{OUT} \times I_{LOAD(MAX)}}{V_{IN} \times \eta}
\]

\[
\Delta I = (30\% - 50\%)I_{IN(MAX)}
\]

Where \( I_{LOAD(MAX)} \) is the maximum load current, \( \Delta I \) is the peak-to-peak inductor ripple current and \( \eta \) is efficiency. For the MP1540, 4.7µH is recommended for input voltages less than 3.3V and 10µH for inputs greater than 3.3V.

Selecting the Diode
The output rectifier diode supplies current to the inductor when the internal MOSFET is off. To reduce losses due to diode forward voltage and recovery time, use a Schottky diode. Choose a diode whose maximum reverse voltage rating is greater than the maximum output voltage. It is recommended to choose the MBR0520 for most applications. This diode is used for load currents less than 500mA. If the average current is more than 500mA the Microsemi UPS5817 is a good choice.
Compensation
The MP1540 uses an amplifier to compensate the feedback loop rather than a traditional transconductance amplifier like most current mode regulators. Frequency compensation is provided by an internal resistor and capacitor along with an external resistor. The system uses two poles and one zero to stabilize the control loop. The poles are \( f_{P1} \) set by the output capacitor and load resistance, and \( f_{P2} \) set by the internal compensation capacitor, the gain of the error amplifier and the resistance seen looking out at the feedback node \( R_{EQ} \). The zero \( f_{Z1} \) is set internally around 20KHz. These are determined by the equations:

\[
f_{P1} = \frac{1}{\pi \times C2 \times R_{LOAD}}
\]

\[
f_{P2} = \frac{1}{2 \times \pi \times (7.9 \times 10^{-9}) \times R_{EQ}}
\]

\[
f_{Z1} = 20\text{KHz}
\]

Where \( R_{LOAD} \) is the load resistance and \( R_{EQ} \) is:

\[
R_{EQ} = R3 + \frac{(R1 \times R2)}{(R1 + R2)}
\]

Where \( R1, R2, \) and \( R3 \) are seen in Figure 2.

The DC loop gain is:

\[
A_{\text{VDC}} = 500 \times \frac{V_{IN} \times R_{LOAD} \times V_{FB}}{V_{OUT}^2}
\]

There is also a right-half-plane zero (\( f_{RHPZ} \)) that exists in all continuous mode (inductor current does not drop to zero on each cycle) step up converters. The frequency of the right half plane zero is:

\[
f_{RHPZ} = \frac{V_{IN}^2 \times R_{LOAD}}{2 \times \pi \times L \times V_{OUT}^2}
\]

To stabilize the regulation control loop, the crossover frequency (the frequency where the loop gain drops to 0dB or a gain of 1, indicated as \( f_c \)) should be at least one decade below the right-half-plane zero and should be at most 75KHz. \( f_{RHPZ} \) is at its lowest frequency at maximum output load current (\( R_{LOAD} \)) at a minimum and minimum input voltage.

For the MP1540 it is recommended that a 47k\( \Omega \) to 100k\( \Omega \) resistor be placed in series with the FB pin and the resistor divider as seen in Figure 2. For most applications this is all that is needed for stable operation. If greater phase margin is needed a series resistor and capacitor can be placed in parallel with the high-side resistor \( R1 \) as seen in Figure 2. The pole and zero set by the lead-lag compensation network are:

\[
f_{P3} = \frac{1}{2 \times \pi \times C3 \times \left( \frac{1}{R4 + \frac{1}{R1 + \frac{1}{R2 + R3}}} \right)}
\]

\[
f_{Z2} = \frac{1}{2 \times \pi \times C3 \times (R1 + R4)}
\]

Layout Considerations
High frequency switching regulators require very careful layout for stable operation and low noise. All components must be placed as close to the IC as possible. Keep the path between \( L1, D1, \) and \( C2 \) extremely short for minimal noise and ringing. \( C1 \) must be placed close to the IN pin for best decoupling. All feedback components must be kept close to the FB pin to prevent noise injection on the FB pin trace. The ground return of \( C1 \) and \( C2 \) should be tied close to the GND pin.
**TYPICAL APPLICATIONS**

![Diagram](image1.png)

Figure 2—$V_{IN} = 5V$, $V_{OUT} = 12V$, $I_{OUT} = 200mA$ Boost Circuit

![Diagram](image2.png)

Figure 3—Typical Application Circuit for Driving Flashlight LEDs (20mA Torch Current, 100mA Flash Current)
PACKAGE INFORMATION

NOTE:

1. Dimensions and tolerances are as per ANSI Y14.5M, 1994.
2. Die is facing up for mold. Die is facing down for trim/form, i.e., reverse trim/form.
3. Dimensions are exclusive of mold flash and gate burr.
4. The footlength measuring is based on the gauge plane method.
5. All specification comply to Jedec Spec MO193 Issue C.